



## Decision Support

Improved bounds for the traveling umpire problem: A stronger formulation and a relax-and-fix heuristic <sup>☆</sup>Lucas de Oliveira <sup>a</sup>, Cid C. de Souza <sup>a</sup>, Tallys Yunes <sup>b,\*</sup><sup>a</sup> Institute of Computing, University of Campinas (UNICAMP), Campinas, SP, Brazil<sup>b</sup> School of Business Administration, University of Miami, Coral Gables, FL, USA

## ARTICLE INFO

## Article history:

Received 29 August 2013

Accepted 11 December 2013

Available online 18 December 2013

## Keywords:

OR in sports

Baseball

Heuristics

Integer programming

Relax-and-fix

Traveling umpire problem

## ABSTRACT

Given a double round-robin tournament, the traveling umpire problem (TUP) consists of determining which games will be handled by each one of several umpire crews during the tournament. The objective is to minimize the total distance traveled by the umpires, while respecting constraints that include visiting every team at home, and not seeing a team or venue too often. We strengthen a known integer programming formulation for the TUP and use it to implement a relax-and-fix heuristic that improves the quality of 24 out of 25 best-known feasible solutions to instances in the TUP benchmark. We also improve all best-known lower bounds for those instances and, for the first time, provide lower bounds for instances with more than 16 teams.

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## 1. Introduction

The assignment of officials (referees, umpires, judges, etc.) to the games of a competition is an important and difficult problem studied in the area of sports scheduling. The specific constraints and objectives vary according to the sport and type of competition, of course, but they typically aim to satisfy a given set of fairness criteria while minimizing costs (e.g. wages or travel). Existing research ranges over many different sports, including baseball (Evans, Hebert, & Deckro, 1984; Evans, 1988; Trick & Yildiz, 2011; Trick & Yildiz, 2012; Trick, Yildiz, & Yunes, 2012), cricket (Wright, 1991), football (Yavuz, İnan, & Fiğlali, 2008), and tennis (Farmer, Smith, & Miller, 2007). For more comprehensive surveys of sports-related problems, we refer to Ernst, Jiang, Krishnamoorthy, Owens, and Sier (2004) and Kendall, Knust, Ribeiro, and Urrutia (2010).

We study the traveling umpire problem (TUP), which was first proposed by Trick and Yildiz (2007) as an abstract version of the real-life umpire scheduling problem faced by Major League

Baseball. Despite excluding many details present in the real problem, the TUP successfully captures the most important features that make the problem very challenging to solve. This is evidenced by the fact that many small instances remain unsolved in the official TUP benchmark: Trick (2013).

Given a double round-robin tournament with  $2n$  teams (each team plays against each other team twice, once at home and once on the road, over exactly  $4n - 2$  rounds), the distances between the home venues of each pair of teams, and two integers  $0 \leq d_1 < n$  and  $0 \leq d_2 < \lfloor \frac{n}{2} \rfloor$ , a solution to the TUP is an assignment of  $n$  umpire crews (umpires, for short) that satisfies the following constraints:

- (i) In each round, each umpire is assigned to exactly one game and each game must be assigned to an umpire;
- (ii) Each umpire visits every team at home at least once;
- (iii) Each umpire visits any given venue at most once in any sequence of  $n - d_1$  consecutive games;
- (iv) Each umpire sees any given team at most once in any sequence of  $\lfloor \frac{n}{2} \rfloor - d_2$  consecutive games.

The objective is to find a feasible solution that minimizes the total distance traveled by the umpires over the entire tournament.

When  $d_1 = d_2 = 0$ , TUP instances tend to be more difficult to solve because constraints (iii) and (iv) become stricter. We refer to these instances as *hard instances*. To allow for a wider range in the degree of difficulty, the TUP benchmark also includes instances with  $d_1 + d_2 > 0$ , to which we refer as *relaxed instances*.

<sup>☆</sup> This research was supported by Grant 01-P-01965-2012 from *Coordenação de Aperfeiçoamento de Pessoal de Nível Superior* (Brazil) and Grants 142278/2013-0, 477692/2012-5 and 302804/2010-2 from *Conselho Nacional de Desenvolvimento Científico e Tecnológico* (Brazil).

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Our main contributions are: (1) we strengthen a known integer programming formulation for the TUP and use it to implement a relax-and-fix heuristic that improves the quality of 24 out of 25 best-known feasible solutions to instances in the TUP benchmark; and (2) using our stronger formulation, we improve all best-known lower bounds for those instances and, for the first time, provide lower bounds for instances with more than 16 teams.

Before explaining our approach in detail, we review the existing exact and heuristic methods for solving the TUP.

### 2. Previous work

Trick and Yildiz (2007) present exact integer programming (IP) and constraint programming (CP) models for the TUP and test them on benchmark instances ranging from 4 to 16 teams, as well as on a 30-team instance. These same models are also used in Trick and Yildiz (2011); Trick and Yildiz (2012); and Trick et al. (2012), but in Trick and Yildiz (2011) and Trick and Yildiz (2012) the performance of the IP model is improved by a better choice of solver parameters (execution times were limited to three hours). Their IP model finds optimal solutions to all instances with at most 10 teams. The CP model finds optimal solutions to all instances with at most 8 teams, and also to one of the four 10-team instances. In addition, it manages to prove that the 12-team instance is infeasible; a conclusion that was not obtained by the IP model within the allowed computation time. When it comes to hard instances with 14 teams, both IP and CP find feasible solutions to all four instances, with the CP model beating the IP model in terms of solution quality in three of the four cases. Neither the IP nor the CP models managed to find any feasible solutions to hard instances with more than 14 teams. When run on relaxed instances, the CP model finds feasible solutions to all eight 14-team and all twelve 16-team instances. The IP model finds feasible solutions to 17 of these 20 instances (three 16-team instances had no solution after 3 hours), but all 17 solutions are better than their counterpart solutions found by the CP model. Neither method managed to find provably optimal solutions to any of the relaxed instances with more than 10 teams.

On the heuristic side, we focus on hard and relaxed instances with at least 14 teams because none of them have known optimal solutions (29 instances in total; 25 with known feasible solutions). Trick et al. (2012) describe a greedy matching heuristic (GMH) and a two-exchange local search that are combined to build a simulated annealing (SA) heuristic. The SA heuristic does reasonably well on the real-life Major League Baseball problem of 2006, but it does not perform so well on the TUP instances. Trick and Yildiz (2011) incorporate the GMH into a large neighborhood search guided by Benders cuts that help repair the solution being built when the heuristic gets stuck. This improved GMH, which they call GBNS, finds feasible solutions to 23 out of 25 instances with previously known solutions, with 16 of those solutions being improvements over the best results at the time. In a follow-up paper, Trick and Yildiz (2012) propose a genetic algorithm (GA) with a crossover operator that uses a matching scheme to recombine the individuals of a population. Their GA further improves the quality of 14 instances with respect to the GBNS results. As of August, 2013, the results published in Trick (2013) indicate that the four best-known solutions to the 14-team hard instances were obtained by Wauters (2013). Table 1 shows how many of the 25 best-known solutions to date have been found by each of the most successful methods described above. The GA currently owns the majority of best-known solutions (13 out of 25), including the best solution to the 30-team instance.

The remainder of this paper is organized as follows. In Section 3, we present the IP formulation of Trick and Yildiz (2011) and show how it can be strengthened. We describe our relax-and-fix heuris-

tic in Section 4, and provide computational results in Section 5. We conclude the paper and discuss future research directions in Section 6.

### 3. IP formulations

For simplicity, we use letters  $i$  and  $j$  to refer to teams  $i$  and  $j$ , as well as their respective home venues. In addition, we use letters  $u$  and  $s$  to refer to an umpire and a round in the tournament, respectively.

#### 3.1. The original formulation

The IP formulation used by Trick and Yildiz (2011); Trick and Yildiz (2012); and Trick et al. (2012) starts with the following input data:

- Set of umpires  $U = \{1, \dots, n\}$ ;
- Set of teams  $T = \{1, \dots, 2n\}$ ;
- Set of rounds  $S = \{1, \dots, 4n - 2\}$ ;
- $OPP[s, i] = \begin{cases} j & \text{if } i \text{ plays against } j \text{ at venue } i \text{ in round } s \\ -j & \text{if } i \text{ plays against } j \text{ at venue } j \text{ in round } s; \end{cases}$
- $d_{ij}$  = distance in miles between venues  $i$  and  $j$ ;
- $CV_s = \{s, \dots, s + n - d_1 - 1\}$  for any given round  $s \in \{1, \dots, 4n - 2 - (n - d_1 - 1)\}$ ;
- $CT_s = \{s, \dots, s + \lfloor \frac{n}{2} \rfloor - d_2 - 1\}$  for any given round  $s \in \{1, \dots, 4n - 2 - (\lfloor \frac{n}{2} \rfloor - d_2 - 1)\}$ .

The decision variables are:

- $x_{isu} = \begin{cases} 1 & \text{if the game at venue } i \text{ in round } s \text{ is assigned} \\ & \text{to umpire } u \\ 0 & \text{otherwise;} \end{cases}$
- $z_{ijsu} = \begin{cases} 1 & \text{if umpire } u \text{ is at venue } i \text{ in round } s \text{ and travels} \\ & \text{to venue } j \text{ in round } s + 10 \text{ otherwise.} \end{cases}$

We are now ready to state the formulation.

$$\min \sum_{i \in T} \sum_{j \in T} \sum_{u \in U} \sum_{s \in S: s < |S|} d_{ij} z_{ijsu} \tag{1}$$

$$\sum_{u \in U} x_{isu} = 1, \quad \forall i \in T, s \in S: OPP[s, i] > 0, \tag{2}$$

$$\sum_{i \in T: OPP[s, i] > 0} x_{isu} = 1, \quad \forall s \in S, u \in U, \tag{3}$$

$$\sum_{s \in S: OPP[s, i] > 0} x_{isu} \geq 1, \quad \forall i \in T, u \in U, \tag{4}$$

$$\sum_{c \in CV_s: OPP[c, i] > 0} x_{icu} \leq 1, \quad \forall i \in T, u \in U, s \in S: s \leq |S| - (n - d_1 - 1), \tag{5}$$

$$\sum_{c \in CT_s} \left( x_{icu} + \sum_{j \in T: OPP[c, j] = i} x_{jcu} \right) \leq 1, \quad \forall i \in T, u \in U, s \in S: s \leq |S| - (\lfloor \frac{n}{2} \rfloor - d_2 - 1), \tag{6}$$

$$x_{isu} + x_{j(s+1)u} - z_{ijsu} \leq 1, \quad \forall i, j \in T, u \in U, s \in S: s < |S|, \tag{7}$$

$$x_{isu} \in \{0, 1\}, \quad \forall i \in T, u \in U, s \in S, \tag{8}$$

$$z_{ijsu} \in \{0, 1\}, \quad \forall i, j \in T, u \in U, s \in S: s < |S|. \tag{9}$$

The objective function (1) minimizes the total distance traveled by the umpires. Constraints (2) and (3) state that each game is refereed by an umpire, and each umpire is assigned to a game, respectively. TUP constraints (ii), (iii), and (iv) from Section 1 are modeled by (4)–(6), respectively. Finally, (7) ensures that game (x) and travel (z) assignments are consistent.

Trick and Yildiz (2011) improve the above formulation by including the following constraints:

**Table 1**  
Number of best-known solutions found by existing solution methods according to the TUP benchmark web site.

Solution method	Instance type/# teams			
	$d_1 = d_2 = 0$		$d_1 + d_2 > 0$	
	14	16	14	16
IP of Trick and Yildiz (2011)			1	2
GBNS of Trick and Yildiz (2011)				5
GA of Trick and Yildiz (2012)			7	6
Wauters (2013b)	4			

$$x_{isu} = 0, \quad \forall i \in T, u \in U, s \in S : \text{OPP}[s, i] < 0, \tag{10}$$

$$z_{ijsu} - x_{isu} \leq 0, \quad \forall i, j \in T, u \in U, s \in S : s < |S|, \tag{11}$$

$$z_{ijsu} - x_{j(s+1)u} \leq 0, \quad \forall i, j \in T, u \in U, s \in S : s < |S|, \tag{12}$$

$$\sum_{j \in T} z_{ijsu} - \sum_{j \in T} z_{ij(s+1)u} = 0, \quad \forall i \in T, u \in U, s \in S : s < |S| - 1, \tag{13}$$

$$\sum_{i \in T} \sum_{j \in T} z_{ijsu} = 1, \quad \forall u \in U, s \in S : s < |S|. \tag{14}$$

Constraint (10) forbids the assignment of an umpire to a venue where no game is played in the given round. Constraints (11) and (12) allow an umpire to move from or to a venue in round  $s$  and  $s + 1$ , respectively, only if the umpire is assigned to the venue in those rounds. The flow conservation constraint (13) states that if umpire  $u$  is (is not) at venue  $i$  in round  $s + 1$ , his trip from round  $s + 1$  to round  $s + 2$  must (must not) start at venue  $i$ . Constraint (14) forces every umpire to move from one round to the next.

Formulation (1)–(14) suffers from symmetry because, given a solution,  $n!$  equivalent solutions can be obtained by permuting the umpires. To overcome this problem, Yildiz (2008) fixes the games refereed by each umpire in a given round  $k$ , which is chosen arbitrarily in the interval  $[1, 4n - 2]$ . To accomplish that, we enforce (15) for a given set  $K$  of tuples that assign each umpire to a different venue where a game takes place in round  $k$ :

$$x_{iku} = 1, \quad \forall (i, u) \in K. \tag{15}$$

We refer to round  $k$  as the *symmetry breaking round*, and to formulation (1)–(15) as  $\mathcal{F}_1$ . The linear relaxation of  $\mathcal{F}_1$ , in which we replace the integrality constraints 8–9 with  $0 \leq x_{isu} \leq 1$  and  $0 \leq z_{ijsu} \leq 1$ , is denoted by  $\mathcal{F}_1^R$ .

### 3.2. A stronger formulation

Based on  $\mathcal{F}_1$ , we propose a stronger formulation for the TUP that includes the following valid identities:

$$x_{i1u} = \sum_{j \in T} z_{ij1u} \quad \forall i \in T, u \in U, \tag{16}$$

$$x_{isu} = \sum_{j \in T} z_{ji(s-1)u} \quad \forall i \in T, u \in U, s \in S : s > 1. \tag{17}$$

Constraint (16) ensures that an umpire  $u$  is assigned to a venue  $i$  in the first round if, and only if,  $u$  travels away from  $i$  in this round. Analogously, (17) enforces that an umpire  $u$  is assigned to a venue  $i$  in round  $s > 1$  if, and only if,  $u$  travels to  $i$  between rounds  $s - 1$  and  $s$ .

Because (16)–(17) are equalities, variable  $x$  can be eliminated from  $\mathcal{F}_1$  by replacing each of its occurrences with the proper summation over  $z$ . Let  $\mathcal{F}_2$  be the formulation that results from  $\mathcal{F}_1$  after both eliminating  $x$  and removing (3), (7), (11), (12), and (14). We refer to the linear relaxation of  $\mathcal{F}_2$  as  $\mathcal{F}_2^R$ .

**Proposition 1.**  $\mathcal{F}_2$  is a valid IP formulation for the TUP.

**Proof.** It suffices to show that (3), (7), (11), (12), and (14) are implied by the conjunction of (16) and (17) with the remaining constraints of  $\mathcal{F}_1$ . For simplicity, and without loss of generality, we will show the implications before eliminating  $x$  from the model.

First, by combining (13) and (16), (17) we obtain the following identity:

$$x_{isu} = \sum_{j \in T} z_{ijsu}, \quad \forall i \in T, u \in U, s \in S : s < |S|. \tag{18}$$

To see that (18) implies (11), note that  $\sum_{j \in T} z_{ijsu} \geq z_{ihsu}$  for any given  $h \in T$ . The proof that (17) implies (12) is analogous.

We now show that (3) and (14) are implied constraints. Because of (13), we can write

$$\sum_{i \in T} \sum_{j \in T} z_{ij1u} = \dots = \sum_{i \in T} \sum_{j \in T} z_{ijk_u} = \dots = \sum_{i \in T} \sum_{j \in T} z_{ij(|S|-1)u}, \quad \forall u \in U, \tag{19}$$

and, by replacing the inner summations in (19) with the appropriate  $x$  variables according to (18), we obtain the equivalent equalities in (20), except for the last one:

$$\sum_{i \in T} x_{i1u} = \dots = \sum_{i \in T} x_{iku} = \dots = \sum_{i \in T} x_{i(|S|-1)u} = \sum_{i \in T} x_{i(|S|)u}, \quad \forall u \in U. \tag{20}$$

To obtain the last equality in (20) we replace the rightmost inner summation in (19) with the appropriate  $x$  variable according to (17).

Because of (15),  $\sum_{i \in T} x_{iku} = 1$ . Thus, all the expressions in (19) and (20) are equal to 1. Since the summations in (19) and (20) are the same as those in (14) and (3), respectively, the latter are satisfied.

Finally, we show that (7) is an implied constraint. For any  $u \in U, s \in S, s < |S|$ , we have seen that combining (15), (19), and (20) yields

$$\sum_{i \in T} \sum_{j \in T} z_{ijsu} = 1.$$

Hence, for a given pair of venues  $i, j$  in the double-summation above, we have

$$\sum_{h \in T: h \neq j} z_{ihsu} + \sum_{h \in T: h \neq i} z_{hj su} + z_{ijsu} \leq 1,$$

which is equivalent to

$$\sum_{h \in T} z_{ihsu} + \sum_{h \in T} z_{hj su} - z_{ijsu} \leq 1. \tag{21}$$

Because of (18), we can substitute  $x_{isu}$  for  $\sum_{h \in T} z_{ihsu}$  in (21). Similarly, (17) allows us to substitute  $x_{j(s+1)u}$  for  $\sum_{h \in T} z_{hj su}$  in (21), turning it into (7).  $\square$

We are now ready to show that  $\mathcal{F}_2$  is stronger than  $\mathcal{F}_1$ .

**Proposition 2.** The lower bound provided by  $\mathcal{F}_2^R$  is greater than or equal to the lower bound provided by  $\mathcal{F}_1^R$ . Moreover, the former bound can be strictly greater than the latter.

**Proof.** From the proof of Proposition 1, it is clear that the lower bound provided by  $\mathcal{F}_2^R$  cannot be worse than the lower bound provided by  $\mathcal{F}_1^R$ . Therefore, it suffices to show an example in which the former bound is strictly greater than the latter. Consider a TUP instance with four teams (represented by a table of games in each

round) as shown in Fig. 1. The first team in each pair (game) is the home team. Suppose that teams 1, 2, and 3 have their venues close to each other (say, 1 mile away), and the venue of team 4 is further away from the others (say, 10 miles away). In this scenario, an optimal solution to  $\mathcal{F}_1^R$  with  $d_1 = d_2 = 0, k = 1$ , and  $K = \{(1, 1), (3, 2)\}$  corresponds to assigning value 1 to variables  $x_{111}$  and  $x_{312}$ , value 0 to variables  $x_{311}$  and  $x_{112}$ , value 0.5 to all other  $x_{isu}$  variables where  $i \in T, s \in S, u \in U$ , and  $OPP[i, s] > 0$ , value 0.5 to variables  $z$  of umpire 1 associated with the trips given by the simple solid and dashed lines in Fig. 1, and value 0.5 to variables  $z$  of umpire 2 associated with the trips given by the simple and double solid lines in Fig. 1. All remaining variables are equal to zero. The optimal value is 25, which is a very weak lower bound because the value of an optimal integer solution to this instance is 55.

Now, observe that (17) is not satisfied by the previous solution because variables  $x_{441}, x_{442}, x_{461}$ , and  $x_{462}$  have value 0.5 and all the  $z$  variables arriving to or leaving from the venue of team 4 in rounds 4 and 6 have value 0. Hence, this fractional solution becomes infeasible once (17) is added to  $\mathcal{F}_1^R$ . In fact, the new optimal solution found after the inclusion of (16) and (17) has value 52, which is much closer to the integer optimum. □

It is possible to strengthen  $\mathcal{F}_2^R$  further by fixing the following variables:

$$z_{isu} = 0, \quad \forall i \in T, u \in U, s \in S : s < |S|, \text{ if } d_1 < n - 1, \quad (22)$$

$$\forall i \neq j \in T, u \in U, s \in S : s < |S|, \text{ if } d_2 < \lfloor \frac{|S|}{2} \rfloor - 1 \text{ and}$$

$$z_{ijsu} = 0, \quad \text{either } OPP[s, i] = OPP[s + 1, j] \text{ or } OPP[s, i] = j \text{ or } OPP[s + 1, j] = i. \quad (23)$$

Note that (22) and (23) are valid because they forbid the assignment of positive values to  $z$  variables that would violate TUP constraints (iii) and (iv) (no umpire can stay at a venue, or follow a team) when  $d_1$  and  $d_2$  are strictly less than their maximum values. Let  $\mathcal{F}_{2+}$  and  $\mathcal{F}_{2+}^R$  be, respectively, the formulations obtained from  $\mathcal{F}_2$  and  $\mathcal{F}_2^R$  after the inclusion of (22) and (23). In the example of Fig. 1, the optimal solution obtained by  $\mathcal{F}_1^R$  (see proof of Proposition 2) violates (22) multiple times. For example, it sets  $z_{2221} = z_{2222} = z_{2231} = z_{2232} = z_{3351} = z_{3352} = 0.5$ . Solving  $\mathcal{F}_{2+}^R$  for that example yields an integer (optimal) solution of value 55. Recall that the lower bounds produced by  $\mathcal{F}_1^R$  and  $\mathcal{F}_2^R$  for that example are 25 and 52, respectively.

#### 4. A relax-and-fix heuristic

A relax-and-fix heuristic iteratively solves relaxations of an IP model and progressively fixes variables until a feasible solution is found (Wolsey, 1998, Section 12.5). Our relax-and-fix heuristic is based on  $\mathcal{F}_{2+}$ . It receives as input a TUP instance and an integer  $1 \leq b \leq 4n - 3$ . The parameter  $b$  defines the size of a window of consecutive rounds whose variables will be binary in the relaxed model solved at each iteration of the algorithm. Starting with formulation  $\mathcal{F}_{2+}$  with the symmetry breaking round  $k = 1$ , we modify it so that only the variables in the first  $b$  rounds are binary. This relaxed model is solved and, if it is infeasible, the algorithm stops. Otherwise, the variables in the first round are fixed to their values in the best solution found within some stopping criteria. In the next iteration, variables in round  $b + 1$  are also made binary and

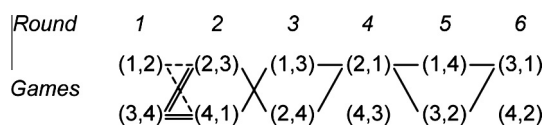


Fig. 1. A TUP instance. Dashed, simple and double solid lines represent umpire trips.

the resulting model is solved. As before, we stop in case of infeasibility, and fix the variables in the second round to their best values otherwise. These steps are repeated until either all variables are fixed, or the model becomes infeasible. The pseudocode in Fig. 2 includes more specific details, which we discuss next.

At iteration  $t$ , the heuristic solves a relaxed  $\mathcal{F}_{2+}$  model in which the  $z$  variables in rounds  $s \leq t - 1, t \leq s < t + b$ , and  $s \geq t + b$  are fixed, binary, and continuous, respectively. If this model is feasible, the variables in round  $t$  are fixed to their values in the best solution found after exploring no more than a given number of search nodes (see Section 5.3 for details). Because intermediate solutions found in line 8 of the pseudocode are not necessarily optimal for the last model solved, the heuristic may continue to execute until iteration  $t = 4n - 3$ , when all variables in the model are fixed.

To keep running times under control, we use two different strategies to solve the relaxations of  $\mathcal{F}_{2+}$  in each iteration of the relax-and-fix heuristic. For instances with at most 18 teams, we solve the models with all variables and constraints, as described above. For instances with more than 18 teams, in each iteration  $t$  of the heuristic we solve a relaxation of  $\mathcal{F}_{2+}$  that only includes the variables and constraints relative to rounds no greater than  $\min(\lfloor \frac{2}{5}(4n - 2) \rfloor + t - 1, 4n - 2)$ . (Recall that, in iteration  $t$ , all variables relative to the  $t - 1$  first rounds are fixed.) This is equivalent to redefining the set  $S$  at each iteration to be  $S = \{1, \dots, \min(\lfloor \frac{2}{5}(4n - 2) \rfloor + t - 1, 4n - 2)\}$ . The value  $\lfloor \frac{2}{5}(4n - 2) \rfloor$  was chosen experimentally with the goal of accelerating the heuristic, while still allowing the model to look at enough rounds ahead of round  $t$  to be able to find good solutions. To properly disregard future rounds while solving relaxations of  $\mathcal{F}_{2+}$ , it is necessary to deal with (4) in a different way. In early iterations, the number of rounds considered by the relaxed  $\mathcal{F}_{2+}$  models is insufficient to satisfy the constraint. If we disregard (4) entirely for many iterations, however, the variables that get fixed may make it impossible to satisfy (4) later on. Therefore, we introduce (4) gradually as follows. We disregard it during iterations  $t \leq n$ . In iterations  $n + 1, n + 2, \dots, 2n - 1$  we enforce (4) only for umpires whose indices are less than or equal to  $1, 2, \dots, n - 1$ , respectively, and in iterations  $t > 2n - 1$  we enforce (4) for all umpires.

Notice that our heuristic begins with a fixed assignment of umpires for the first round ( $k = 1$ ) and, at each iteration  $t$ , determines the umpire trips between rounds  $t$  and  $t + 1$ . This resembles the GMH of Trick et al. (2012). The difference stems from the fact that our relax-and-fix heuristic schedules the umpires in each round while taking into account, in a relaxed way, the subsequent rounds of the tournament. In addition, we deal with the trip distances directly, rather than using a modified cost function to schedule each round. Finally, because our method is not guaranteed to find a solution every time, we could use a backtracking scheme similar to what is done with the GMH. In practice, however, we almost always find solutions to the instances that are known to be feasible.

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1: procedure RELAX-AND-FIX(TUP instance I, b)
2:    $\mathcal{M} \leftarrow \mathcal{F}_{2+}$  model with  $k = 1$  for instance I;
3:    $t \leftarrow 1$ ;
4:   while  $t \leq 4n - 3$  do
5:     For all  $i, j \in T, u \in U, s \in S, t \leq s < t + b$ , let  $z_{ijsu} \in \{0, 1\}$  in  $\mathcal{M}$ ;
6:     For all  $i, j \in T, u \in U, s \in S, s \geq t + b$ , let  $0 \leq z_{ijsu} \leq 1$  in  $\mathcal{M}$ ;
7:     Solve  $\mathcal{M}$ ;
8:     if a solution  $\bar{z}_{ijsu}$  is found within the allowable # of search nodes then
9:       Fix variables  $z_{ijsu} = \bar{z}_{ijsu}$  for all  $i, j \in T, u \in U, s = t$ ;
10:       $t \leftarrow t + 1$ ;
11:    else
12:      return no solution;
13:    end if
14:  end while
15:  return solution found;
16: end procedure

```

Fig. 2. Pseudocode of the relax-and-fix heuristic.

Therefore, to keep our implementation simple, we decided not to use a backtracking step.

## 5. Computational results

In this section, we experimentally evaluate the IP models and the relax-and-fix heuristic presented earlier. We consider instances from the TUP benchmark (Trick, 2013) ranging from 4 to 32 teams. Instance names start with the number of teams, optionally followed by a letter indicating that the distance matrix is different, but the underlying tournament is not. Experiments were performed on a machine running Linux Ubuntu 12.04.1 and equipped with an i7-2600, 3.40 GHz processor, and 8 GB of RAM. Our code is written in C++, and we use ILOG CPLEX's callable library version 12.5.0.1 to solve linear programming and integer programming models.

### 5.1. IP results on hard instances: Lower and upper bounds

Before solving the IP models, we analyze the strength of our lower bounds. We focus first on hard instances ( $d_1 = d_2 = 0$ ), and fix the symmetry breaking round  $k = 1$ . Table 2 shows the lower bounds obtained by solving the linear relaxations of the original IP model ( $\mathcal{F}_1^R$ ) and of our stronger formulations ( $\mathcal{F}_2^R$ ) and ( $\mathcal{F}_{2+}^R$ ). We also include the solution time and the optimal distances for instances with known optimal solutions. Note that, except for the smallest instance (4 teams),  $\mathcal{F}_2^R$  and  $\mathcal{F}_{2+}^R$  always provide better lower bounds than  $\mathcal{F}_1^R$ . In particular,  $\mathcal{F}_{2+}^R$  provides significantly better bounds (up to 340% better) that are reasonably close to the known optimal solutions, which attests the importance of (22) and (23). In addition,  $\mathcal{F}_2^R$  and  $\mathcal{F}_{2+}^R$  solve between 2 and 8 times faster than  $\mathcal{F}_1^R$  because they are more compact (fewer variables and constraints), with  $\mathcal{F}_{2+}^R$  having a slight advantage over  $\mathcal{F}_2^R$ .

Our experiments show that the choice of the symmetry breaking round  $k$  can significantly affect the value of the lower bound

provided by the linear relaxations. However, it is difficult to determine a priori what value of  $k$  leads to the best results for the integer models. Therefore, we solve the IP models with three different values of  $k$ : 1 (first round),  $2n - 1$  (middle round), and the value  $k^*$  that produces the best lower bound. The models adjusted with each chosen value of  $k$  are denoted as before but followed by the suffixes “-F” (first-round  $k$ ), “-M” (middle-round  $k$ ) and “-BB” (best-bound  $k$ ), respectively.

We now switch from root-node lower bounds to solving the IP models, while still focusing on hard instances. We limit execution times to 3 hours and limit the number of CPU threads to one. Table 3 shows the optimal distances and execution times for hard instances with 12 or fewer teams. In general,  $\mathcal{F}_{2+}$  exhibits better performance than  $\mathcal{F}_1$ . For a given formulation, breaking symmetry in the middle round often speeds up the optimization, whereas breaking symmetry in the first round tends to be a bad idea. Therefore, we disregard  $\mathcal{F}_1$ -F and  $\mathcal{F}_{2+}$ -F in subsequent experiments.

Table 4 summarizes the results for hard instances with at least 14 teams, which have no known optimal solutions. Calculating  $k^*$  for  $\mathcal{F}_1$ -BB on instances with at least 26 teams, and for  $\mathcal{F}_{2+}$ -BB on instance 32 takes longer than 3 hours. In these cases, we report the best lower bound found within 3 hours, which is marked with an “\*”, and do not execute CPLEX's branch-and-cut. The lower bounds in Table 4 contain unexpected results for  $\mathcal{F}_1$ . Although  $\mathcal{F}_1^R$  does not perform well in Table 2, it appears that the root-node presolve and strengthening routines of CPLEX are able to improve it, enabling  $\mathcal{F}_1$  to achieve competitive lower bounds in 3 hours. For example, the best lower bounds for instances with 16 and 18 teams are given by  $\mathcal{F}_1$ -BB. On the other hand, this model yields very poor lower bounds for instances with more than 24 teams within the time limit. The  $\mathcal{F}_{2+}$  models achieve the best lower bounds on instances with 14 teams, or with more than 18 teams, with the latter being significantly better than those provided by the  $\mathcal{F}_1$  models. Overall,  $\mathcal{F}_{2+}$ -BB obtains 8 out of the 16 best lower bounds,

**Table 2**  
Lower bounds from the linear relaxations of different IP models of hard instances ( $d_1 = d_2 = 0$ ) with  $k = 1$ .

Instance	Optimum	Lower bound			Time (seconds)		
		$\mathcal{F}_1^R$	$\mathcal{F}_2^R$	$\mathcal{F}_{2+}^R$	$\mathcal{F}_1^R$	$\mathcal{F}_2^R$	$\mathcal{F}_{2+}^R$
4	5176	5176.0	5176.0	5176.0	0.0	0.0	0.0
6	14,077	5874.3	7971.0	14077.0	0.0	0.0	0.0
6A	15,457	7351.0	9228.0	13672.3	0.0	0.0	0.0
6B	16,716	6541.0	9766.0	15786.3	0.0	0.0	0.0
6C	14,396	5097.7	6717.3	14396.0	0.0	0.0	0.0
8	34,311	11836.7	14787.3	33723.2	0.1	0.0	0.0
8A	31,490	11659.4	13792.4	30193.9	0.0	0.0	0.0
8B	32,731	11057.2	15408.7	31724.4	0.0	0.0	0.0
8C	29,879	10717.6	12532.7	27718.3	0.0	0.0	0.0
10	48,942	16781.1	20026.1	48040.1	0.2	0.1	0.1
10A	46,551	13261.6	14991.3	44909.8	0.2	0.1	0.1
10B	45,609	13832.1	17358.5	44238.7	0.2	0.1	0.1
10C	43,149	14922.3	16594.7	39618.2	0.2	0.1	0.1
12		26993.5	39722.3	82753.4	0.6	0.3	0.3
14		43664.2	68706.4	140180.0	1.7	0.8	0.9
14A		42484.1	67680.4	132063.0	1.7	0.9	0.8
14B		41587.2	63116.8	129671.0	1.8	0.8	0.8
14C		45634.8	68155.2	125719.0	2.0	0.9	0.8
16		46133.6	65830.9	131264.0	6.1	2.3	2.0
16A		51454.1	76574.5	145901.0	5.5	2.3	2.0
16B		48635.1	86315.4	143592.0	6.1	2.6	2.0
16C		36402.5	81699.4	144402.0	4.8	2.1	1.9
18		49031.3	88031.7	152548.0	14.2	4.2	4.0
20		47183.0	92467.9	183820.0	40.4	9.3	8.0
22		55629.1	109778.0	209092.0	73.4	21.2	15.2
24		56630.0	119211.0	226090.0	136.9	35.2	28.9
26		59919.4	129532.0	266366.0	302.3	69.3	47.1
28		72861.6	161630.0	302138.0	463.9	100.3	85.9
30		83710.2	166316.0	338267.0	1169.8	170.7	143.6
32		97058.9	186105.0	371968.0	1786.5	322.0	227.8

**Table 3**Optimal results obtained by IP formulations on hard instances with at most 12 teams ( $d_1 = d_2 = 0$ ).

Instance	Optimum	Time (seconds)					
		$\mathcal{F}_1$ -F	$\mathcal{F}_1$ -M	$\mathcal{F}_1$ -BB	$\mathcal{F}_{2+}$ -F	$\mathcal{F}_{2+}$ -M	$\mathcal{F}_{2+}$ -BB
4	5176	0.00	0.00	0.00	0.00	0.00	0.00
6	14,077	0.02	0.02	0.02	0.02	0.01	0.02
6A	15,457	0.05	0.02	0.03	0.02	0.01	0.01
6B	16,716	0.03	0.03	0.04	0.02	0.02	0.02
6C	14,396	0.02	0.02	0.03	0.01	0.01	0.02
8	34,311	0.53	0.06	0.15	0.38	0.03	0.03
8A	31,490	0.30	0.06	0.05	0.24	0.03	0.02
8B	32,731	0.30	0.06	0.06	0.12	0.02	0.02
8C	29,879	0.65	0.06	0.04	0.53	0.03	0.02
10	48,942	38.10	1.68	1.64	14.56	1.17	1.87
10A	46,551	52.05	4.77	5.48	21.25	1.00	4.27
10B	45,609	25.52	2.32	3.59	5.67	0.73	0.73
10C	43,149	335.33	9.19	13.54	34.49	2.78	1.92
12	Infeasible	3172.34	101.10	857.48	2556.69	71.47	627.42

**Table 4**Best results for the IP models on hard instances with at least 14 teams ( $d_1 = d_2 = 0$ ). Execution times limited to 3 hour. Best values appear in bold.

Instance	Best lower bound after 3 hour				Best solution after 3 hour			
	$\mathcal{F}_1$ -M	$\mathcal{F}_1$ -BB	$\mathcal{F}_{2+}$ -M	$\mathcal{F}_{2+}$ -BB	$\mathcal{F}_1$ -M	$\mathcal{F}_1$ -BB	$\mathcal{F}_{2+}$ -M	$\mathcal{F}_{2+}$ -BB
14	149,636	149,963	150,045	<b>150,871</b>	179,343	177,139	175,524	<b>174,715</b>
14A	142,394	142,759	<b>143,517</b>	141,308	166,712	172,367	<b>165,968</b>	171,961
14B	141,795	141,608	141,645	<b>142,614</b>	172,828	176,709	<b>168,659</b>	170,804
14C	141,196	141,148	<b>141,268</b>	138,601	168,037	168,787	<b>164,512</b>	167,898
16	148,059	<b>151,748</b>	147,906	150,523				
16A	161,087	<b>166,626</b>	160,831	166,101				
16B	158,322	<b>162,251</b>	159,324	161,882				
16C	162,640	<b>165,431</b>	162,505	164,235				
18	171,264	<b>177,055</b>	173,815	175,321				
20	198,706	199,460	201,769	<b>204,278</b>				
22	222,713	228,074	224,841	<b>231,809</b>				
24	246,620	248,817	248,977	<b>253,506</b>				
26	283,971	73,900*	286,239	<b>286,847</b>				
28	312,655	87,273*	317,629	<b>319,044</b>				
30	343,013	94,713*	<b>352,258</b>	344,831				
32	371,143	97,059*	377,531	<b>382,508*</b>				

**Table 5**Best results for the IP models on relaxed instances with at least 14 teams ( $d_1 + d_2 > 0$ ). Execution times limited to 3 hour. Best values appear in bold.

Instance	$n - d_1$	$\lfloor \frac{n}{2} \rfloor - d_2$	Best lower bound after 3 hour				Best solution after 3 hour			
			$\mathcal{F}_1$ -M	$\mathcal{F}_1$ -BB	$\mathcal{F}_{2+}$ -M	$\mathcal{F}_{2+}$ -BB	$\mathcal{F}_1$ -M	$\mathcal{F}_1$ -BB	$\mathcal{F}_{2+}$ -M	$\mathcal{F}_{2+}$ -BB
14	6	3	149,422	<b>150,041</b>	149,883	149,904	167,931	167,800	<b>164,169</b>	165,975
14	5	3	149,446	<b>150,270</b>	149,541	150,194	160,069	160,591	161,905	<b>159,511</b>
14A	6	3	143,138	143,207	<b>143,931</b>	142,456	163,872	163,622	<b>159,054</b>	161,201
14A	5	3	142,230	142,321	<b>143,504</b>	142,600	158,604	158,878	<b>154,840</b>	159,703
14B	6	3	141,839	142,196	142,608	<b>143,378</b>	165,052	164,691	<b>158,050</b>	164,089
14B	5	3	142,117	142,237	<b>143,706</b>	143,147	157,907	157,174	<b>154,739</b>	157,724
14C	6	3	140,967	141,213	<b>141,791</b>	140,393	163,934	159,388	<b>153,841</b>	157,034
14C	5	3	141,717	141,299	141,558	<b>141,801</b>	154,944	156,541	<b>152,046</b>	153,178
16	8	2	142,005	143,420	142,019	<b>143,840</b>	185,505	<b>183,167</b>	206,299	186,108
16	7	3	143,780	144,265	144,325	<b>145,987</b>	207,226	<b>188,486</b>	190,281	195,551
16	7	2	138,027	137,443	139,888	<b>141,440</b>	177,925	167,697	170,288	<b>163,193</b>
16A	8	2	155,542	157,013	155,743	<b>157,972</b>	216,598	199,684	194,050	<b>190,233</b>
16A	7	3	156,544	159,146	157,393	<b>160,314</b>	210,267	<b>205,345</b>	209,604	215,136
16A	7	2	152,063	154,563	154,023	<b>155,342</b>	186,439	180,372	<b>176,793</b>	182,317
16B	8	2	152,675	157,356	153,734	<b>158,035</b>	<b>206,044</b>	212,300	240,845	208,859
16B	7	3	154,667	157,955	155,988	<b>158,244</b>	<b>215,692</b>	237,571		217,261
16B	7	2	151,406	155,173	152,218	<b>155,403</b>	203,491	192,062	191,213	<b>184,991</b>
16C	8	2	157,239	158,164	158,051	<b>160,596</b>	205,626	<b>192,741</b>	213,953	205,095
16C	7	3	159,916	160,438	159,970	<b>161,838</b>	211,880	<b>206,505</b>	222,039	223,262
16C	7	2	156,421	156,810	157,357	<b>158,527</b>	186,989		182,307	<b>182,011</b>
30	5	5	336,470	75,891*	<b>367,877</b>	361,175				

**Table 6**  
Solutions obtained by the relax-and-fix heuristic on relaxed instances with at least 14 teams. Best values appear in bold.

Instance	$n - d_1$	$\lfloor \frac{n}{2} \rfloor - d_2$	Width of shifting window of binary variables (parameter $b$ )									
			1	2	3	4	5	6	7	8	9	10
14	7	3	No sol.	178,226	174,652	168,408	170,629	169,981	168,408	<b>165,573</b>	166,942	170,250
14	6	3	165,529	165,764	<b>159,522</b>	163,818	159,622	162,377	160,907	159,601	164,450	163,573
14	5	3	160,913	158,103	156,442	158,054	158,293	156,456	157,942	157,404	<b>155,439</b>	155,958
14A	7	3	168,422	171,938	166,357	164,136	160,830	163,471	163,860	164,784	<b>160,046</b>	163,433
14A	6	3	No sol.	156,183	157,219	162,614	158,619	156,437	158,237	157,034	158,133	<b>154,628</b>
14A	5	3	153,955	154,251	154,218	154,891	152,588	154,441	<b>149,331</b>	149,956	152,855	152,490
14B	7	3	No sol.	173,698	162,952	162,634	160,242	163,629	<b>157,884</b>	162,305	<b>157,884</b>	163,329
14B	6	3	162,891	163,161	158,818	157,927	157,222	<b>153,611</b>	158,291	155,358	158,382	158,735
14B	5	3	156,321	155,125	153,724	<b>150,268</b>	150,865	151,251	150,933	150,760	150,954	153,202
14C	7	3	176,479	174,595	166,559	163,227	160,262	160,274	163,720	<b>159,518</b>	164,778	161,049
14C	6	3	164,223	155,523	158,304	<b>152,158</b>	154,954	154,026	155,025	155,435	154,366	155,200
14C	5	3	153,697	151,914	<b>149,662</b>	150,415	149,727	150,346	151,048	150,678	150,471	151,426
16	8	2	168,647	168,094	166,688	<b>160,705</b>	161,771	167,482	163,733	164,187	165,098	167,015
16	7	3	No sol.	181,556	177,557	<b>169,994</b>	174,009	170,487	172,549	179,940	173,088	177,242
16	7	2	163,438	157,184	153,996	158,043	157,379	155,796	155,766	154,153	158,130	<b>153,978</b>
16A	8	2	183,344	174,841	178,320	173,956	175,092	176,821	<b>173,950</b>	176,664	176,266	174,546
16A	7	3	186,667	193,983	185,198	188,957	183,192	192,059	182,889	<b>181,119</b>	188,879	188,475
16A	7	2	177,235	165,675	168,224	167,010	168,058	<b>164,620</b>	168,032	170,486	167,538	168,810
16B	8	2	187,840	186,326	187,514	185,223	186,853	185,541	<b>182,673</b>	184,750	183,238	185,253
16B	7	3	207,308	194,064	189,257	191,234	188,064	191,026	187,488	188,198	189,596	<b>187,007</b>
16B	7	2	183,841	172,083	171,962	172,704	172,336	172,688	<b>170,194</b>	172,169	172,274	173,143
16C	8	2	193,358	184,873	181,205	<b>180,221</b>	182,568	184,103	182,706	187,598	185,487	184,753
16C	7	3	189,776	No sol.	188,855	191,021	187,649	<b>185,528</b>	189,251	189,367	No sol.	194,055
16C	7	2	174,744	174,401	172,033	171,802	170,909	<b>169,184</b>	170,267	171,046	172,319	170,854
30	5	5	<b>466,765</b>	484,447	479,056	475,572	487,552	471,724	No sol.	No sol.	No sol.	No sol.

**Table 7**  
Execution times (seconds) for the relax-and-fix heuristic on relaxed instances with at least 14 teams.

Instance	$n - d_1$	$\lfloor \frac{n}{2} \rfloor - d_2$	Width of shifting window of binary variables (parameter $b$ )											
			1	2	3	4	5	6	7	8	9	10	4, 6, 7	1–10
14	7	3	157	254	339	501	716	947	1099	1238	1528	1815	2547	8594
14	6	3	147	262	302	599	721	953	1106	1181	1424	1336	2657	8031
14	5	3	125	192	278	493	725	810	989	944	1053	1112	2291	6721
14A	7	3	179	383	511	722	775	1132	1376	1647	1703	1743	3231	10,171
14A	6	3	159	348	485	578	898	1053	1356	1374	1404	1546	2988	9201
14A	5	3	150	254	397	640	802	931	1099	1227	1316	1319	2670	8134
14B	7	3	170	331	504	497	785	901	1232	1405	1386	1641	2631	8852
14B	6	3	170	303	524	677	925	1172	1290	1453	1552	1579	3139	9645
14B	5	3	150	272	434	680	917	1096	1170	1170	1251	1331	2946	8472
14C	7	3	151	334	608	681	889	1062	1342	1346	1578	1674	3085	9665
14C	6	3	151	271	476	539	736	1068	1244	1371	1433	1434	2851	8723
14C	5	3	137	227	384	588	775	995	1045	1198	1241	1223	2629	7813
16	8	2	701	1398	1596	1711	2022	2287	2529	2968	3079	3077	6528	21,369
16	7	3	722	1577	1876	2231	3264	4073	4417	5199	5710	6073	10,721	35,143
16	7	2	771	1293	1620	2169	2572	2800	2901	3239	3628	3584	7869	24,577
16A	8	2	848	1333	1676	1729	2200	2259	2351	2818	3045	2954	6339	21,213
16A	7	3	954	1690	1952	2718	3311	3537	4473	4830	5591	6506	10,728	35,560
16A	7	2	821	1110	1984	2099	2272	2379	3089	3191	3469	3819	7567	24,232
16B	8	2	927	1633	1861	1985	2325	2577	2934	2968	3305	3396	7495	23,911
16B	7	3	935	1464	1939	2536	2981	4265	4296	4519	5534	5832	11,097	34,301
16B	7	2	872	1316	1950	2128	2499	2948	2996	3525	3438	4112	8072	25,784
16C	8	2	844	1326	1563	1892	1842	2211	2671	2791	3187	3557	6774	21,884
16C	7	3	764	1188	1812	2433	2721	3235	3991	4615	1122	4836	9659	26,717
16C	7	2	834	1151	1558	1780	1948	2437	2729	2893	3012	3200	6947	21,543
30	5	5	16,352	13,817	11,825	10,821	8397	14,917	5208	4841	5033	6455	30,946	97,666

and gets reasonably close in the remaining cases, except for instance 30. The best lower bounds shown in Table 4 are better than the best known bounds reported in the TUP benchmark, for all instance sizes. In particular, the benchmark reports no lower bounds for instances with more than 16 teams.

When it comes to quality of feasible solutions, no formulation finds solutions to hard instances with more than 14 teams (no such solutions are known, to the best of our knowledge). Formulation  $\mathcal{F}_{2+}$ -M finds three out of the four best 14-team solutions, all of which are better than the best known solutions found by exact methods reported in Trick and Yildiz (2012).

5.2. IP results on relaxed instances: Lower and upper bounds

Table 5 summarizes the performance of our IP models on relaxed instances ( $d_1 + d_2 > 0$ ) with at least 14 teams. Because calculating  $k^*$  for the 30-team instance with  $\mathcal{F}_1$ -BB takes too long, we report the best lower bound found within 3 hours and mark it with an “\*”. Except for the first two 14-team instances, the lower bounds provided by  $\mathcal{F}_{2+}$  models are always better than those provided by  $\mathcal{F}_1$  models. The  $\mathcal{F}_{2+}$ -BB model is responsible for 14 out of the 21 best lower bounds, and its solution is reasonably close to the best bound in the remaining cases. Formulation  $\mathcal{F}_{2+}$ -M does well

**Table 8**

Comparison between the best results obtained by our exact and heuristic approaches and the best results from literature on hard and relaxed instances with at least 14 teams.

Instance	$n - d_1$	$\lfloor \frac{n}{2} \rfloor - d_2$	Lower bounds				Solution values				
			Lit. Best	$\mathcal{F}_{2+}^R$ -BB	$\mathcal{F}_{2+}$ -BB	$\mathcal{F}$ Best	Lit. Best	$\mathcal{F}$ Best	RF Worst	RF 4,6,7	RF Best
14	7	3	141,253	143,089	150,871	150,871	166,964	174,715	178,226	168,408	165,573
14	6	3	141,064	142,716	149,904	150,041	173,681	164,169	165,764	160,907	159,522
14	5	3	141,134	142,478	150,194	150,270	165,558	159,511	160,913	156,456	155,439
14A	7	3	133,279	135,149	141,308	143,517	160,407	165,968	171,938	163,471	160,046
14A	6	3	133,194	134,971	142,456	143,931	164,857	159,054	162,614	156,437	154,628
14A	5	3	133,023	134,884	142,600	143,504	162,380	154,840	154,891	149,331	149,331
14B	7	3	131,373	131,684	142,614	142,614	161,129	168,659	173,698	157,884	157,884
14B	6	3	130,799	131,542	143,378	143,378	168,476	158,050	163,161	153,611	153,611
14B	5	3	130,628	131,301	143,147	143,706	160,443	154,739	156,321	150,268	150,268
14C	7	3	126,843	131,163	138,601	141,268	159,461	164,512	176,479	160,274	159,518
14C	6	3	126,613	130,921	140,393	141,791	166,395	153,841	164,223	152,158	152,158
14C	5	3	126,427	130,556	141,801	141,801	163,662	152,046	153,697	150,346	149,662
16	8	4	134,471	134,151	150,523	151,748					
16	8	2	134,347	132,563	143,840	143,840	178,775	183,167	168,647	160,705	160,705
16	7	3	121,933	127,593	145,987	145,987	185,966	188,486	181,556	169,994	169,994
16	7	2	121,670	126,946	141,440	141,440	166,114	163,193	163,438	155,766	153,978
16A	8	4	148,377	147,551	166,101	166,626					
16A	8	2	146,992	145,595	157,972	157,972	188,432	190,233	183,344	173,950	173,950
16A	7	3	137,178	142,945	160,314	160,314	199,016	205,345	193,983	182,889	181,119
16A	7	2	137,806	142,056	155,342	155,342	172,728	176,793	177,235	164,620	164,620
16B	8	4	146,646	146,805	161,882	162,251					
16B	8	2	145,058	145,383	158,035	158,035	201,039	206,044	187,840	182,673	182,673
16B	7	3	139,833	141,838	158,244	158,244	202,395	215,692	207,308	187,488*	187,007
16B	7	2	139,742	141,552	155,403	155,403	184,923	184,991	183,841	170,194	170,194
16C	8	4	145,012	152,698	164,235	165,431					
16C	8	2	144,398	150,451	160,596	160,596	202,023	192,741	193,358	180,221	180,221
16C	7	3	142,467	148,932	161,838	161,838	213,157	206,505	194,055	185,528	185,528
16C	7	2	142,399	148,481	158,527	158,527	181,013	182,011	174,744	169,184	169,184
30	5	5	336,124	361,175	367,877	367,877	483,224		487,552	471,724*	466,765

with 14-team instances, finding 4 out of the 8 best lower bounds, and it also finds the best bound for the 30-team instance. When it comes to feasible solutions,  $\mathcal{F}_{2+}$ -M manages to find 8 out of the 21 best solutions.

The best lower bounds shown in Table 5 are better than the best known bounds reported in the TUP benchmark, for *all* instance sizes. In addition, 18 out of the 20 best solutions shown in Table 5 are better than the best solutions found by *exact* methods reported in Trick and Yildiz (2012). More importantly, 11 of these solutions (underlined numbers) are better than the best known solution found by *any* method, according to the TUP benchmark. In Section 5.3, we show that our heuristic can do even better than that.

### 5.3. Heuristic results

We use CPLEX to solve the optimization models inside the relax-and-fix heuristic (see Table A.9 in A for the parameter settings we used). We apply the relax-and-fix heuristic with  $b = 1, 2, \dots, 10$  to the instances used in our previous experiments. The heuristic finds an optimal solution to all but one of the hard instances with at most 10 teams. (The best solution obtained by the heuristic for instance 10C is 43,193, which is close to the optimal distance of 43,149.) The total time spent to obtain these solutions for all values of  $b$  is at most 1 second for instances with 4 and 6 teams, at most 10 seconds for instances with 8 teams, at most 2 minutes for instances 10, 10A, and 10B, and around 3 minutes for instance 10C. Tables 6 and 7 present, respectively, the solution values and execution times for hard and relaxed instances with at least 14 teams. Unfortunately, similarly to previous attempts reported in the literature, the relax-and-fix heuristic does not manage to find feasible solutions to hard instances with more than 14 teams. For the instances to which it manages to find a feasible solution, the heuristic appears to be reliable, obtaining solutions in 240 out of 250 runs (25 instances, 10 values of  $b$ ). Most of the best solutions (14 out of 25) are found with  $b = 4, 6$ , or 7. Finally, we also include in Table 7

the total cumulative time to find the solutions for  $b \in \{4, 6, 7\}$  (column “4,6,7”) and for  $b \in \{1, 2, \dots, 10\}$  (column “1–10”).

### 5.4. Best results

We now compare the best results obtained by our approaches (exact and heuristic) with the best results from the literature, which are published in Trick and Yildiz (2011); Trick and Yildiz (2012); Trick et al. (2012); and Trick (2013). The most relevant comparison for hard instances with no more than 10 teams are the times required to reach optimality. Table 3 indicates that our strengthened formulation  $\mathcal{F}_{2+}$  does better than  $\mathcal{F}_1$  on these small instances, and that a good choice of  $k$  (e.g. middle-round) pays off.

The main improvements we achieve are on instances with at least 14 teams, which have no known optimal solutions. Table 8 summarizes the best results for these instances (an “\*” indicates that the time limit was exceeded; see Table 7). The best lower bounds and solutions from the literature were obtained within 3 hours of computation for instances with 14 and 16 teams, and within 5 hours for the relaxed 30-team instance (solution only; no lower bound is reported). The lower bounds provided by  $\mathcal{F}_{2+}^R$ -BB are already better than the best ones in the literature on 25 out of 29 instances. They can be calculated in less than 1 minute for instances with at most 16 teams, and in approximately 2 hours for the instance with 30 teams. Within 3 hours of computation, the best lower bounds found during branch-and-cut with  $\mathcal{F}_{2+}$ -BB beat all known lower bounds by margins ranging between 8 and 24 thousand miles. The “ $\mathcal{F}$  Best” column under “Lower bounds” shows the best bounds we managed to find over the entire range of models we considered. These bounds are better than the  $\mathcal{F}_{2+}$ -BB bounds on 13 out of 29 instances.

On the right half of Table 8 we compare the quality of the best known solutions in the literature with those obtained by our IP models and by the relax-and-fix heuristic. All of our best solutions are obtained by some configuration of the relax-and-fix heuristic



(column “RF Best”). The only instance whose solution we do not manage to improve is 14C-7-3 (by a mere 57 miles). For the remaining 24 instances with known feasible solutions, our best solutions are between 0.36 and 27.6 thousand miles shorter. When compared with the best solutions obtained by the IP models (column “ $\mathcal{F}$  Best”), the best relax-and-fix solutions are between 1.68 and 28.6 thousand miles shorter. However, except for instances with 14 teams, this comparison is unfair because finding the best relax-and-fix solution over all values of  $b \in \{1, 2, \dots, 10\}$  takes much more time than the limits of 3 and 5 hours (see Table 7). Therefore, we include column “RF 4,6,7” which has the best solution obtained over three runs of relax-and-fix with  $b = 4, 6,$  and  $7$ . These three runs obtain most of our best results (14 out of 25) and, in total, stay within the time limits with two exceptions: instance 16B-7-3 (3-hour limit exceeded by 5 minutes), and instance 30. When compared to the best known solutions in the literature, solutions under “RF 4,6,7” have less mileage in 22 out of 25 cases. The worst solutions obtained by the relax-and-fix heuristic (column “RF Worst”) are better than the best known solutions in 18 out of 25 cases. Finally, for the relaxed instance with 30 teams, 4 out of the 6 solutions found by the relax-and-fix heuristic are better than the best one in the literature, with the greatest improvement being equal to 16,459 miles.

## 6. Conclusions and future work

By strengthening an existing IP formulation for the traveling umpire problem (TUP), we obtain an optimization model that not only solves more quickly than its original version, but also provides better lower and upper bounds for instances in the TUP benchmark. This new formulation plays a crucial role in our implementation of a relax-and-fix heuristic for the problem, because each iteration of the heuristic cannot dedicate too much time to solving its intermediate IP models. As a result, we improve all known lower bounds for instances in the benchmark, as well as 24 of the 25 best known upper bounds. Moreover, we are the first to provide strong lower bounds for instances with more than 16 teams.

The TUP remains a very difficult problem, with many small instances lacking feasible solutions. We believe that a combination of exact and heuristic methods is a promising research direction. The TUP formulations deserve a deeper polyhedral study, and our relax-and-fix heuristic can be modified in several ways. For example, the sliding windows of binary variables can take different shapes, focus first on problematic areas of the schedule (a bottleneck approach), and/or use randomization. Finally, not much attention has been given to improving the CP model of Trick and Yildiz (2011), and a more effective version of that model (e.g. with fancier search routines) could become part of a relax-and-fix heuristic as well.

We hope that the improvements in solution quality presented in this paper will spark the interest of other researchers in tackling this challenging problem.

**Table A.9**

CPLEX branch-and-cut parameters used to solve the models inside the relax-and-fix heuristic.

Parameter	≤18 Teams	>18 Teams
Number of parallel threads	1	1
MIP node limit	100	100
MIP repeat presolve	Off	Off
MIP heuristic frequency	2	
RINS heuristic frequency	20	
Feasibility pump heuristic	On	
SubMIP node limit	10	
MIP probing level	Very aggressive	
MIP dive strategy	Probing dive	
MIP integer solution limit		1

## Appendix A

See Table A.9.

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